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**Об одной сумме интегральных преобразований
Ганкеля–Клиффорда функций Уиттекера**

Джунесанг Чой, А. И. Нижников, И. А. Шилин

Джунесанг Чой — доктор наук, заслуженный профессор Донггукского университета (г. Кёнджу, Республика Корея).

e-mail: junesang@dongguk.ac.kr

Нижников Александр Иванович — кандидат физико-математических наук, профессор, заведующий кафедрой прикладной математики, информатики и ИТ, Московский педагогический государственный университет (г. Москва).

e-mail: ainizhnikov@mail.ru

Шилин Илья Анатольевич — кандидат физико-математических наук, доцент, доцент кафедры высшей математики НИУ МЭИ и кафедры алгебры, Московский педагогический государственный университет (г. Москва).

e-mail: ilyashilin@li.ru

Аннотация

В статье [11] авторами рассматривалась реализация T представления группы $SO(2, 2)$ в одном пространстве однородных функций, заданных на 2×4 -матрицах. Настоящее продолжение этой статьи посвящено вычислению матричных элементов тождественного оператора $T(e)$ и операторов представления $T(g)$ для подходящих элементов g группы относительно смешанного базиса, соответствующего двум различным базисам пространства представления, и вычислению некоторых несобственных интегралов, содержащих произведение функций Бесселя–Клиффорда и Уиттекера. Полученные результаты могут быть переписаны на языке интегральных преобразований Ганкеля–Клиффорда и их аналога. Первое и второе преобразования Ганкеля–Клиффорда, введенные соответственно Хайеком и Перезом–Робайней, играют важную роль в теории дифференциальных операторов дробного порядка (см., например, [6, 8]). Близкий результат получен авторами недавно [12] для регулярной кулоновской функции.

Ключевые слова: группа $SO(2, 2)$, матричные элементы представления, интегральные преобразования Ганкеля–Клиффорда, интегральное преобразование Макдональда–Клиффорда, функции Уиттекера, функции Бесселя–Клиффорда.

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On one sum of Hankel–Clifford integral transforms of Whittaker functions

J. Choi, A. I. Nizhnikov, I. A. Shilin

Junesang Choi — Doctor of Sciences, Emeritus Professor of Dangguo University (Gyeongju, Republic of Korea).

e-mail: junesang@dongguk.ac.kr

Nizhnikov Alexander Ivanovich — candidate of physical and mathematical Sciences, Professor, Head of the Department of Applied Mathematics, Computer Science and IT, Moscow State Pedagogical University (Moscow).

e-mail: ainizhnikov@mail.ru

Shilin Ilya Anatolevich — candidate of physical and mathematical Sciences, Associate Professor, Department of Higher Mathematics, NRU MEI and the Department of Algebra, Moscow State Pedagogical University (Moscow).

e-mail: ilyashilin@li.ru

Abstract

In [11], the authors considered the realization T of $SO(2, 2)$ -representation in a space of homogeneous functions on 2×4 -matrices. In this sequel, we aim to compute matrix elements of the identical operator $T(e)$ and representation operator $T(g)$ for an appropriate g with respect to the mixed basis related to two different bases in the $SO(2, 2)$ -carrier space and evaluate some improper integrals involving a product of Bessel-Clifford and Whittaker functions. The obtained result can be rewritten in terms of Hankel-Clifford integral transforms and their analogue. The first and the second Hankel-Clifford transforms introduced by Hayek and Pérez–Robayna, respectively, play an important role in the theory of fractional order differential operators (see, e.g., [6, 8]). The similar result have been derived recently by the authors for the regular Coulomb function in [12].

Keywords: group $SO(2, 2)$, matrix elements of representation, Hankel-Clifford integral transform, Macdonald-Clifford integral transform, Whittaker functions, Bessel-Clifford functions.

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1. Introduction and preliminaries

We recall the definitions and notations in [11]. The group $SO(2, 2)$, which preserves the quadratic form \mathcal{E} defined in \mathbb{R}^4 whose matrix with respect to the canonical basis is a diagonal matrix $e_{2,2} = \text{diag}(1, 1, -1, -1)$, which is called the split orthogonal group and consists of real 4×4 matrices g satisfying the equality $g e_{2,2} g^t = e_{2,2}$. Here and throughout, let \mathbb{C} , \mathbb{R} , \mathbb{R}^+ , \mathbb{R}^- , \mathbb{Z} and \mathbb{N} be the sets of complex numbers, real numbers, positive real numbers, negative real numbers, integers and positive integers, respectively, and let $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$. Let L be a real linear space

consisting of real 2×4 matrices. We define the cone Λ in L by the subset of matrices of rank 2 satisfying the equation $x e_{2,2} x^t = \text{diag}(0,0)$. Let \mathfrak{L} be the complex linear space consisting of infinitely differentiable functions defined on Λ and satisfying the equality $f(bx) = |b_{11}|^{\sigma_1} |b_{22}|^{\sigma_2} f(x)$ for a fixed pair $(\sigma_1, \sigma_2) \in \mathbb{C}^2$ and arbitrary non-degenerate matrix $b = \begin{pmatrix} b_{11} & 0 \\ b_{21} & b_{22} \end{pmatrix}$. We consider the $SO(2,2)$ -representation T in \mathfrak{L} defined by formula $T(g)[f(x)] = f(xg)$. In [14], with a view to investigating some special functions of matrix argument, this construction has been used.

Shilin and Choi [11] dealt with the spherical section ω_1 of Λ consisting of matrices

$$\tilde{x}(\alpha_1, \beta_1) = \begin{pmatrix} \cos \alpha_1 & -\sin \alpha_1 & \cos \beta_1 & -\sin \beta_1 \\ \sin \alpha_1 & \cos \alpha_1 & \sin \beta_1 & \cos \beta_1 \end{pmatrix} \quad (\alpha_1, \beta_1 \in [0, 2\pi)). \quad (1)$$

In particular, they [11] showed that for any $x \in \Lambda$ there are a low triangular non-degenerate 2×2 -matrix b and $\tilde{x} \in \omega_1$ such that $x = b\tilde{x}$. If \mathfrak{L}_1 is the linear space of restrictions of functions $f \in \mathfrak{L}$ on ω_1 , we can realize the representations T as the same representation in \mathfrak{L}_1 . They also showed that the function $f = \exp(ip_1\alpha_1)\exp(iq_1\beta_1)$ defined on ω_1 does not belong to $f = \exp(ip_1\alpha_1)\exp(iq_1\beta_1)$ if and only if the sum $p_1 + q_1$ is not divisible by 2, and defined the canonical basis

$$\tilde{B}_1 = \{\tilde{f}_{p_1, q_1}(\alpha_1, \beta_1) = \exp(ip_1\alpha_1)\exp(iq_1\beta_1) \mid p_1, q_1 \in \mathbb{Z}, p_1 + q_1 \equiv 0 \pmod{2}\},$$

which is orthonormal with respect to the scalar product

$$f * g = \frac{1}{4\pi^2} \int_0^{2\pi} \int_0^{2\pi} f(\alpha_1, \beta_1) \overline{g(\alpha_1, \beta_1)} d\alpha_1 d\beta_1$$

in \mathfrak{L}_1 . Writing Cartan decomposition $g = g_1 g_2 g_3$ for an arbitrary element g of the group $SO(2,2)$, where $g_1, g_3 \in SO(2) \times SO(2)$ and

$$g_2 \in \exp \begin{pmatrix} 0 & \text{diag}(\mu, \nu) \\ \text{diag}(\mu, \nu) & 0 \end{pmatrix},$$

they showed that in case $|\nu| \neq |\mu|$ the matrix elements of the linear operator $T(g)$ with respect to \tilde{B}_1 can be written as a product of four exponential functions, depending respectively on four parameters of the rotations g_1 and g_3 , and two Gaussian hypergeometric functions depending (respectively) on $(\tanh \frac{\mu \pm \nu}{2})^2$.

The parabolic section ω_2 of Λ has been defined as the subset consisting of matrices

$$\tilde{x}(\alpha_2, \beta_2) = \begin{pmatrix} 1 & \alpha_2 & \cos \beta_2 - \alpha_2 \sin \beta_2 & \sin \beta_2 + \alpha_2 \cos \beta_2 \\ 0 & 1 & -\sin \beta_2 & \cos \beta_2 \end{pmatrix},$$

where $\alpha_2 \in \mathbb{R}$ and $\beta_2 \in [0, 2\pi)$. If \mathfrak{L}_2 is the linear space of restrictions of functions $f \in \mathfrak{L}$ on ω_2 , then the canonical basis in \mathfrak{L}_2 can be defined as follows:

$$\tilde{B}_2 = \{\tilde{f}_{p_2, q_2}(\alpha_2, \beta_2) = \exp(ip_2\alpha_2)\exp(iq_2\beta_2) \mid p_2 \in \mathbb{R}, q_2 \in [0, 2\pi)\}.$$

They [11] established the one-to-one correspondence between the restrictions of $T(g)$ to \mathfrak{L}_2 and integral operators whose kernels can be described in terms of some Bessel functions.

2. Two bases in \mathfrak{L} and our purpose

Let us denote the determinant $\det \begin{pmatrix} x_{1m} & x_{1n} \\ x_{2m} & x_{2n} \end{pmatrix}$ inside the matrix $x \in \Lambda$ by $\Delta_{m,n}$ and introduce the basis

$$B_1 = \{f_{p_1, q_1}(x) \mid p_1, q_1 \in \mathbb{Z}, p_1 + q_1 \equiv 0 \pmod{2}\}$$

in \mathfrak{L} , consisting of functions

$$f_{p_1, q_1}(x) = (x_{11}^2 + x_{12}^2)^{\frac{\sigma_1 - \sigma_2 + q_1 - p_1}{2}} |\Delta_{1,2}|^{\sigma_2 - q_1} (x_{11} - ix_{12})^{p_1 - q_1} (\Delta_{1,3} + i\Delta_{1,4})^{q_1}.$$

Obviously the restriction of f_{p_1, q_1} to ω_1 coincides with $i^{q_1} \tilde{f}_{p_1, -q_1}$:

$$f_{p_1, q_1}|_{\omega_1} = i^{q_1} \tilde{f}_{p_1, -q_1}. \quad (2)$$

In this paper, we also use the basis

$$B_2 = \{f_{p_2, q_2}(x) \mid p_2 \in \mathbb{R}, q_2 \in \mathbb{Z}\},$$

where

$$f_{p_2, q_2}(x) = |x_{11}|^{\sigma_1 - \sigma_2} |\Delta_{1,2}|^{\sigma_2 - q_2} (\Delta_{1,3} + i\Delta_{1,4})^{q_2} \exp \frac{ip_2 x_{12}}{x_{11}}.$$

It is easy to see that f_{p_2, q_2} is an extension of the function $i^{q_2} \tilde{f}_{p_2, q_2}$ to Λ .

Let $\text{span}(f_{p_1, q_1}, f_{\hat{p}_1, \hat{q}_1})$ be the subspace in \mathfrak{L}_1 . It is invariant with respect to the linear operator $T(g)$ (for some fixed g) and its basis vectors f_{p_1, q_1} and $f_{\hat{p}_1, \hat{q}_1}$ which are not eigenfunctions of this operator. In this paper, we aim to establish dependence between the matrix elements of the operator $T(g)$ with respect to the *ordinary* basis B_2 and the *mixed* basis $B_2|B_1$ and matrix elements of the operator $\text{id} \equiv T(e)$ with respect to $B_2|B_1$. Choosing here the group element as follows:

$$h^* = \text{diag} \left(\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \text{diag}(1, 1) \right),$$

we will show that the above dependence can be rewritten as a representation of Whittaker function of the second kind in the form of integral involving Whittaker and Bessel-Clifford functions. The Bessel-Clifford functions are used, for example, for solution of wave equation [1] and are a particular case of more generalized so-called Bessel-Maitland functions (see [8]).

The above-described approach, together with other methods, was used by Shilin and Choi [10] who considered another realization of the representation of the group $SO(2, 2)$ and representation operators corresponding to some diagonal and block-diagonal matrices which belong to the split orthogonal group.

3. Transitive subgroups and invariant measures

It is obvious that ω_1 is an orbit of the subgroup $H_1 \simeq SO(2) \times SO(2)$, consisting of the matrices

$$h_1(\varphi_1, \psi_1) = \begin{pmatrix} \cos \varphi_1 & -\sin \varphi_1 & 0 & 0 \\ \sin \varphi_1 & \cos \varphi_1 & 0 & 0 \\ 0 & 0 & \cos \psi_1 & -\sin \psi_1 \\ 0 & 0 & \sin \psi_1 & \cos \psi_1 \end{pmatrix}.$$

Let us consider the matrices

$$h(\varrho) = \begin{pmatrix} 2 & \varrho & 0 & \varrho \\ -\varrho & 2 & \varrho & 0 \\ 0 & \varrho & 2 & \varrho \\ \varrho & 0 & -\varrho & 2 \end{pmatrix}$$

and the points $\tilde{x}(\alpha_2, \beta_2)$ and $\tilde{x}(\hat{\alpha}_2, \hat{\beta}_2)$ belong to the subset ω_2 of Λ . Since the matrix elements $h_{ij}(\varrho)$ of the matrix $h(\varrho)$ satisfy the equalities

$$h_{i1}(\varrho) + h_{i2}(\varrho) - h_{i3}(\varrho) - h_{i4}(\varrho) = 4 \text{sign}(2.5 - i),$$

we get $\frac{1}{2}h(\varrho) \in SO(2, 2)$. It is easy to see that

$$\begin{aligned}\tilde{x}(\alpha_2, \beta_2)h_1(0, -\beta_2) &= \tilde{x}(\alpha_2, 0) \equiv \begin{pmatrix} 1 & \alpha_2 & 1 & \alpha_2 \\ 0 & 1 & 0 & 1 \end{pmatrix}, \\ \frac{1}{2}\tilde{x}(\alpha_2, 0)h(\hat{\alpha}_2 - \alpha_2) &= \tilde{x}(\hat{\alpha}_2, 0)\end{aligned}$$

and

$$\tilde{x}(\hat{\alpha}_2, 0)h_1(0, \hat{\beta}_2) = \tilde{x}(\hat{\alpha}_2, \hat{\beta}_2).$$

Thus the matrix

$$h_2(\hat{\alpha}_2 - \alpha_2, \hat{\beta}_2 - \beta_2) = \frac{1}{2}h_1(0, -\beta_2)h(\hat{\alpha}_2 - \alpha_2)h_1(0, \hat{\beta}_2)$$

transforms the point $\tilde{x}(\alpha_2, \beta_2)$ into the point $\tilde{x}(\hat{\alpha}_2, \hat{\beta}_2)$. It means that the subgroup

$$H_2 = \{h_2(\varphi_2, \psi_2) \mid \varphi_2 \in \mathbb{R}, \psi_2 \in [0; 2\pi)\}$$

acts transitively on ω_2 . Also we find that $d\omega_2 = d\alpha_1 d\beta_2$ is an H_2 -invariant measure on ω_2 . It is found that f_{p_2, q_2} is an eigenfunction of the linear operator $T(h_2(\varphi_2, \psi_2))$, more exactly,

$$T(h_2(\varphi_2, \psi_2))[f_{p_2, q_2}] = \exp(\mathbf{i})f_{p_2, q_2}.$$

Similarly $d\omega_1 = d\alpha_1 d\beta_1$ is an H_1 -invariant measure on the spherical section ω_1 and f_{p_1, q_1} is an eigenfunction of the operator $T(h_1(\varphi_1, \psi_1))$, namely

$$T(h_1(\varphi_1, \psi_1))[f_{p_1, q_1}] = \exp(\mathbf{i}p_1\varphi_1)\exp(\mathbf{i}q_1\psi_1)f_{p_1, q_1}.$$

4. Functionals F_1 and F_2 and assorted spaces

Let us introduce the following bilinear functionals defined on the direct product $\mathfrak{L} \times \mathfrak{L}^\bullet$ of two representation spaces:

$$F_i : (u, v^\bullet) \mapsto \iint_{\omega_i} u(\alpha_i, \beta_i) v^\bullet(\alpha_i, \beta_i) d\omega_i \quad (i = 1, 2),$$

where the functions on \mathfrak{L}^\bullet are $(\sigma_1^\bullet, \sigma_2^\bullet)$ -homogeneous.

LEMMA 1. *The functional F_1 coincides with F_2 if and only if*

$$\sigma_1^\bullet - \sigma_2^\bullet = \sigma_2 - \sigma_1 - 4. \quad (3)$$

ДОКАЗАТЕЛЬСТВО. It was shown in [11] that for any point $x \in \Lambda$ there are a low triangular non-degenerate 2×2 -matrix b_x and the point $\tilde{x}(\alpha_2, \beta_2)_x \in \omega_2$ such that $x = b_x \tilde{x}(\alpha_2, \beta_2)_x$, and $b_{11} = x_{11}$, $b_{21} = x_{21}$, $\alpha_2 = \frac{x_{12}}{x_{11}}$. In particular, for an arbitrary point (1) belonging to ω_1 , we have

$$b_{\tilde{x}(\alpha_1, \beta_1)} = \begin{pmatrix} \cos \alpha_1 & 0 \\ \sin \alpha_1 & \sec \alpha_1 \end{pmatrix},$$

and, therefore, the correspondence $\tilde{x}(\alpha_1, \beta_1) \mapsto \tilde{x}(\alpha_2, \beta_2)_{\tilde{x}(\alpha_1, \beta_1)}$ is one-to-one. Since the operands $u \in \mathfrak{L}$ and $v^\bullet \in \mathfrak{L}^\bullet$ of the functional F_1 are (σ_1, σ_2) - and $(\sigma_1^\bullet, \sigma_2^\bullet)$ -homogeneous, respectively, we have

$$u(\alpha_1, \beta_1) v^\bullet(\alpha_1, \beta_1) = (\cos \alpha_1)^{\sigma_1 + \sigma_1^\bullet - \sigma_2 - \sigma_2^\bullet} u(\alpha_2, \beta_2) v^\bullet(\alpha_2, \beta_2).$$

Considering that ω_1 -coordinates depend on ω_2 -coordinates according to the formulae

$$\alpha_1 = \arccos \left(\pm \frac{1}{\sqrt{1 + \alpha_2^2}} \right), \quad \beta_1 = \arctan \frac{\alpha_2 \cos \beta_2 + \sin \beta_2}{\alpha_2 \sin \beta_2 - \cos \beta_2}, \quad \left| \frac{\partial(\alpha_1, \alpha_2)}{\partial(\alpha_2, \alpha_2)} \right| = (1 + \alpha_2^2)^{-1},$$

we get

$$\mathsf{F}_1(u, v^\bullet) = \iint_{\omega_1} u(\alpha_1, \beta_1) v^\bullet(\alpha_1, \beta_1) d\alpha_1 d\beta_1 = \iint_{\omega_2} \frac{u(\alpha_2, \beta_2) v^\bullet(\alpha_2, \beta_2) d\alpha_2 d\beta_2}{(1 + \alpha_2^2)^{\sigma_1 + \sigma_1^\bullet - \sigma_2 - \sigma_2^\bullet + 4}}.$$

It is clear that the equality $\mathsf{F}_1 = \mathsf{F}_2$ is equivalent to $\sigma_1 + \sigma_1^\bullet - \sigma_2 - \sigma_2^\bullet + 4 = 0$. \square

Further we assume that representation spaces \mathfrak{L} and \mathfrak{L}^\bullet are *mutually assorted*, i.e., the pair $(\sigma_1^\bullet, \sigma_2^\bullet)$ for the representation space \mathfrak{L}^\bullet is connected with the pair (σ_1, σ_2) for \mathfrak{L} by the equality (3).

5. Matrix elements of the $B_1^\bullet \rightarrow B_2^\bullet$ basis transformation

Let us express the function f_{p_2, q_2} as a linear combination of the functions belonging to the basis B_2^\bullet :

$$f_{p_2, q_2}^\bullet(x) = \sum_{p_1, q_1 \in \mathbb{Z}} c_{p_1, q_1, p_2, q_2} f_{p_1, q_1}^\bullet(x). \quad (4)$$

In view of Lemma 1, we have

$$\mathsf{F}_2(f_{p_2, q_2}^\bullet, f_{\hat{p}_1, \hat{q}_1}) = \sum_{p_1, q_1 \in \mathbb{Z}} c_{p_1, q_1, p_2, q_2} \mathsf{F}_1(f_{p_1, q_1}^\bullet, f_{\hat{p}_1, \hat{q}_1}).$$

Since

$$\mathsf{F}_1(f_{p_1, q_1}^\bullet, f_{\hat{p}_1, \hat{q}_1}) = \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \exp(i[p_1 + \hat{p}_1]\alpha_1) \exp(i[q_1 + \hat{q}_1]\beta_1) d\alpha_1 d\beta_1,$$

we obtain

$$c_{p_1, q_1, p_2, q_2} = \frac{1}{4\pi^2} \mathsf{F}_2(f_{p_2, q_2}^\bullet, f_{-p_1, -q_1}).$$

We compute the matrix elements of the linear operator acting in \mathfrak{L}^\bullet and transforming the basis B_1^\bullet into B_2^\bullet , asserted by the following theorem.

TEOPEMA 1. Let $p_1, q_1, q_2 \in \mathbb{Z}$, $p_2 \in \mathbb{R} \setminus \{0\}$, and $\operatorname{Re}(\sigma_1 - \sigma_2) > -3$. Then

$$\begin{aligned} c_{p_1, q_1, p_2, q_2} &= 2^{\frac{\sigma_2 - \sigma_1}{2} - 3} \pi^{-1} \delta_{q_1, -q_2} |p_2|^{\frac{\sigma_1 - \sigma_2}{2} + 1} \\ &\times \left[\Gamma \left(\frac{\sigma_1 - \sigma_2 + (q_1 - p_1) \operatorname{sign} p_2}{2} \right) \right]^{-1} W_{\frac{(q_1 - p_1) \operatorname{sign} p_2}{2}, \frac{\sigma_2 - \sigma_1 - 3}{2}} (2|p_2|), \end{aligned} \quad (5)$$

where Γ is the gamma function, $W_{\mu, \nu}$ is the Whittaker function of the second kind, and $\delta_{s,t}$ is the Kronecker symbol.

ДОКАЗАТЕЛЬСТВО. Using iterated integrals for

$$\begin{aligned} \mathsf{F}_2(f_{p_2, q_2}^\bullet, f_{-p_1, -q_1}) &= i^{q_1 + q_2} \int_{-\infty}^{\infty} \int_{-\pi}^{\pi} (1 + \alpha_2^2)^{\frac{\sigma_2 - \sigma_1 - p_1 + q_1}{2} - 2} (1 - i\alpha_2)^{p_1 - q_1} \\ &\times \exp(i[p_2\alpha_2 + (q_1 + q_2)\beta_2]) d\alpha_2 d\beta_2, \end{aligned}$$

we find that c_{p_1, q_1, p_2, q_2} can be expressed as an exponential Fourier transform:

$$\begin{aligned} \mathsf{F}_2(f_{p_2, q_2}, f_{-p_1, -q_1}^{\bullet}) &= 2\pi \delta_{q_1, -q_2} \int_{-\infty}^{\infty} (1 + i\alpha_2)^{\frac{\sigma_2 - \sigma_1 + q_1 - p_1}{2} - 2} \\ &\quad \times (1 - i\alpha_2)^{\frac{\sigma_2 - \sigma_1 + p_1 - q_1}{2} - 2} \exp(ip_2\alpha_2) d\alpha_2. \end{aligned} \quad (6)$$

The integral in (6) can be evaluated by the following known formulae (see, e.g., [4, Entry 3.2.(12)])

$$\begin{aligned} \int_{-\infty}^{\infty} (\alpha + ix)^{-2\mu} (\beta - ix)^{-2\nu} \exp(-ixy) dx &= 2\pi(\alpha + \beta)^{-\nu - \mu} [\Gamma(2\nu)]^{-1} \\ &\quad \times \exp\left(\frac{(\beta - \alpha)y}{2}\right) y^{\nu + \mu - 1} W_{\nu - \mu, \frac{1}{2} - \nu - \mu}([\alpha + \beta]y) \\ &\quad \left(\text{Re}(\mu + \nu) > \frac{1}{2}, \min\{\text{Re}(\alpha), \text{Re}(\beta)\} > 0; y \in \mathbb{R}^+ \right) \end{aligned} \quad (7)$$

and

$$\begin{aligned} \int_{-\infty}^{\infty} (\alpha + ix)^{-2\mu} (\beta - ix)^{-2\nu} \exp(-ixy) dx &= 2\pi(\alpha + \beta)^{-\mu - \nu} [\Gamma(2\mu)]^{-1} \\ &\quad \times \exp\left(\frac{(\alpha - \beta)y}{2}\right) (-y)^{\nu + \mu - 1} W_{\mu - \nu, \frac{1}{2} - \nu - \mu}(-[\alpha + \beta]y) \\ &\quad \left(\text{Re}(\mu + \nu) > \frac{1}{2}, \min\{\text{Re}(\alpha), \text{Re}(\beta)\} > 0; y \in \mathbb{R}^- \right). \end{aligned} \quad (8)$$

□

6. Matrix elements of the operator $T^{\bullet}(h^*)$ with respect to B_2^{\bullet}

For any $g \in SO(2, 2)$, let $t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(g)$ be a matrix element of the linear operator $T^{\bullet}(g)$ with respect to the basis B_2^{\bullet} , that is,

$$T^{\bullet}(g)[f_{p_2, q_2}^{\bullet}] = \sum_{\hat{q}_2 \in \mathbb{Z}} \int_0^{\infty} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(g) f_{\hat{p}_2, \hat{q}_2}^{\bullet} d\hat{p}_2. \quad (9)$$

In view of Lemma 1, we get

$$\begin{aligned} \mathsf{F}_i(T^{\bullet}(g)[f_{p_2, q_2}^{\bullet}], f_{\tilde{p}_2, \tilde{q}_2}) &= \sum_{\hat{q}_2 \in \mathbb{Z}} \int_0^{\infty} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(g) \mathsf{F}_2(f_{\hat{p}_2, \hat{q}_2}^{\bullet}, f_{\tilde{p}_2, \tilde{q}_2}) d\hat{p}_2 \\ &= 4\pi^2 \int_0^{\infty} t_{p_2, q_2, \hat{p}_2, -\tilde{q}_2}^{\bullet}(g) \delta(\hat{p}_2 + \tilde{p}_2) d\hat{p}_2, \end{aligned}$$

where $\delta(\hat{p}_2 + \tilde{p}_2)$ is the $(-\tilde{p}_2)$ -delayed Dirac delta function. We therefore have

$$t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(g) = \frac{1}{4\pi^2} \mathsf{F}_i(T^{\bullet}(g)[f_{p_2, q_2}^{\bullet}], f_{-\hat{p}_2, -\hat{q}_2}).$$

In Theorem 2, we show that the matrix elements $t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(h^*)$ can be described in terms of either Bessel–Clifford functions of the first kind

$$\mathcal{C}_{\nu}(z) = z^{-\frac{\nu}{2}} J_{\nu}(2\sqrt{z}) \quad (10)$$

or modified Bessel–Clifford functions of the second kind

$$\mathcal{K}_{\nu}(z) = z^{-\frac{\nu}{2}} K_{\nu}(2\sqrt{z}) \quad (11)$$

depending on $\text{sign}(p_2 \hat{p}_2)$ in both cases (see [2]). Here J_{ν} and K_{ν} are Bessel functions of the first kind and modified Bessel functions of the second kind, respectively, (see, e.g., [13, Chapter 9]).

THEOREM 2. Let $p_2, \hat{p}_2 \in \mathbb{R} \setminus \{0\}$, $q_2, \hat{q}_2 \in [0, 2\pi)$, and $2 < \operatorname{Re}(\sigma_2 - \sigma_1) < 4$. Then

$$\begin{aligned} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(h^*) &= -\frac{2i^{q_2} \delta_{q_2, \hat{q}_2}}{\pi} |p_2|^{\sigma_2 - \sigma_1 - 3} \sin \frac{(\sigma_2 - \sigma_1)\pi}{2} \mathcal{K}_{\sigma_2 - \sigma_1 - 3}(-p_2 \hat{p}_2) \\ &\quad (p_2 \hat{p}_2 \in \mathbb{R}^-) \end{aligned} \quad (12)$$

and

$$\begin{aligned} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(h^*) &= \frac{i^{q_2} \delta_{q_2, \hat{q}_2}}{2} \cos \frac{(\sigma_2 - \sigma_1)\pi}{2} \\ &\quad \times [|p_2|^{\sigma_1 - \sigma_2 + 3} \mathcal{C}_{\sigma_1 - \sigma_2 + 3}(p_2 \hat{p}_2) - |p_2|^{\sigma_2 - \sigma_1 - 3} \mathcal{C}_{\sigma_2 - \sigma_1 - 3}(p_2 \hat{p}_2)] \\ &\quad (p_2 \hat{p}_2 \in \mathbb{R}^+). \end{aligned} \quad (13)$$

ДОКАЗАТЕЛЬСТВО. Since the right shift of the subset ω_2 by the matrix h^* permutes the first and the second columns of any point belonging to ω_2 , we have

$$T(h^*)[f_{p_2, q_2}(x)] = |x_{12}|^{\sigma_1 - \sigma_2} |\Delta_{1,2}|^{\sigma_2 - q_2} (\Delta_{2,3} + i\Delta_{2,4})^{q_2} \exp\left(-\frac{ip_2 x_{11}}{x_{12}}\right).$$

In view of Lemma 1, the $T^{\bullet}(h^*)$ -image of the restriction of f_{p_2, q_2}^{\bullet} to ω_2 is given as follows:

$$T^{\bullet}(h^*)[\tilde{f}_{p_2, q_2}](\alpha_2, \beta_2) = (-1)^{q_2} |\alpha_2|^{\sigma_2 - \sigma_1 - 4} \exp(iq_2 \beta_2) \exp\left(-\frac{ip_2}{\alpha_2}\right).$$

We obtain

$$\begin{aligned} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(h^*) &= \frac{1}{4\pi^2} \mathsf{F}_2(T^{\bullet}(h^*)[f_{p_2, q_2}^{\bullet}], f_{-\hat{p}_2, -\hat{q}_2}) \\ &= \frac{i^{2q_2 - \hat{q}_2}}{4\pi^2} \int_{-\pi}^{\pi} \exp(i[q_2 - \hat{q}_2]\beta_2) d\beta_2 \int_{-\infty}^{+\infty} |\alpha_2|^{\sigma_2 - \sigma_1 - 4} \exp\left(-i\left[\hat{p}_2 \alpha_2 + \frac{p_2}{\alpha_2}\right]\right) d\alpha_2. \end{aligned}$$

Considering here the principle value of the last integral and using the following known formulae (see, e.g., [9, Entires 2.5.24.4 and 2.5.24.7])

$$\int_0^{\infty} x^{\alpha-1} \cos\left(ax + \frac{b}{x}\right) dx = \frac{\pi}{2} \left(\frac{b}{a}\right)^{\frac{\alpha}{2}} \sin\left(\frac{\alpha\pi}{2}\right) \left[J_{-\alpha}(2\sqrt{ab}) - J_{\alpha}(2\sqrt{ab})\right]$$

and

$$\begin{aligned} \int_0^{\infty} x^{\alpha-1} \cos\left(ax - \frac{b}{x}\right) dx &= 2 \left(\frac{b}{a}\right)^{\frac{\alpha}{2}} \cos\left(\frac{\alpha\pi}{2}\right) K_{\alpha}(2\sqrt{ab}) \\ &\quad (a, b \in \mathbb{R}^+; |\operatorname{Re}(\alpha)| < 1), \end{aligned}$$

with the aid of (10) and (11), we complete the proof. \square

7. Matrix elements of the operator $T^{\bullet}(h^*)$ with respect to the mixed basis $f_{p_2, q_2}|f_{p_1, q_1}$

From (2) and (9), we find

$$T^{\bullet}(g)[f_{p_2, q_2}^{\bullet}] = \sum_{p_1, q_1 \in \mathbb{Z}} \left(\sum_{\hat{q}_2 \in \mathbb{Z}} \int_{-\infty}^{\infty} t_{p_2, q_2, \hat{p}_2, \hat{q}_2}^{\bullet}(g) c_{p_1, q_1, \hat{p}_2, \hat{q}_2} d\hat{p}_2 \right) f_{p_1, q_1}^{\bullet}. \quad (14)$$

The expression in the brackets in (14) can be characterised as a matrix element of the operator $T^\bullet(h^*)$ with respect to the so-called mixed basis $f_{p_2,q_2}|f_{p_1,q_1}$ (see, e.g., [3, p. 204]).

On the other hand, these matrix elements may be obtained in the following way. It is not hard to check that the linear subspace $\text{span}(\tilde{f}_{p_1,q_1}, \tilde{f}_{2q_1-p_1,q_1})$ in \mathfrak{L}_1 is invariant with respect to the linear operator $T^\bullet(h^*)$, namely, in view of (2),

$$T^\bullet(h^*)[f_{p_1,q_1}^\bullet|_{\omega_1}] = T(h^*)[\tilde{f}_{p_1,q_1}] = i^{p_1+q_1} \exp(i[p_1\alpha_1 - q_1\beta_1]) = i^{p_1} f_{p_1,q_1}^\bullet|_{\omega_1}. \quad (15)$$

THEOREMA 3. Let $p_1, q_1 \in \mathbb{Z}$ such that $p_1 + q_1 \equiv 0 \pmod{2}$, $p_2 \in \mathbb{R}^+$, and $1 < \text{Re}(\theta) < 2$. Then

$$\begin{aligned} & \int_0^\infty \left[\frac{1}{2} \cos(\theta\pi) p_2^{\theta-1} \hat{p}_2^{4-3\theta} \mathcal{C}_{3-2\theta}(p_2\hat{p}_2) W_{\frac{q_1-p_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \right. \\ & \quad - \frac{1}{2} \cos(\theta\pi) p_2^{3\theta-4} \hat{p}_2^{1-\theta} \mathcal{C}_{2\theta-3}(p_2\hat{p}_2) W_{\frac{q_1-p_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \\ & \quad \left. + (-1)^\theta \frac{2\Gamma(\frac{q_1-p_1}{2} - \theta)}{\pi\Gamma(\frac{p_1-q_1}{2} - \theta)} \sin(\theta\pi) p_2^{3\theta-4} \hat{p}_2^{1-\theta} \mathcal{K}_{2\theta-3}(p_2\hat{p}_2) W_{\frac{p_1-q_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \right] d\hat{p}_2 \\ & = (-1)^{\frac{p_1+q_1}{2}} W_{\frac{q_1-p_1}{2}, \theta-\frac{3}{2}}(2p_2). \end{aligned}$$

ДОКАЗАТЕЛЬСТВО. From (14) and (15) we have

$$T^\bullet(h^*)[f_{p_2,q_2}^\bullet] = \sum_{p_1,q_1 \in \mathbb{Z}} c_{p_1,q_1,p_2,q_2} T^\bullet(g)[f_{p_1,q_1}^\bullet] = \sum_{p_1,q_1 \in \mathbb{Z}} i^{p_1} c_{p_1,q_1,p_2,q_2} f_{p_1,q_1}^\bullet. \quad (16)$$

Since the matrix element c_{p_1,q_1,p_2,q_2} is equal to zero in case $q_1 \neq -q_2$ and the matrix element $t_{p_2,q_2,\hat{p}_2,\hat{q}_2}^\bullet(h^*)$ is equal to zero in case $q_2 \neq \hat{q}_2$, considering (14) and (16), we have

$$\int_{-\infty}^\infty t_{p_2,-q_1,\hat{p}_2,-q_1}^\bullet(h^*) c_{p_1,q_1,\hat{p}_2,-q_1} d\hat{p}_2 = i^{p_1} c_{p_1,q_1,p_2,-q_1}. \quad (17)$$

Using, for (16), the results from Theorems 1 and 2, and letting $\theta = \frac{\sigma_2 - \sigma_1}{2}$, we complete the proof. \square

8. Concluding Remarks

Setting $p_1 = q_1 = 0$ in (14) and considering the following relation between Macdonald functions K_ν and Whittaker functions $W_{0,\nu}$ (see, e.g., Entry [15, 7.8.8]):

$$K_\nu \left(\frac{z}{2} \right) = \left(\frac{\pi}{z} \right)^{\frac{1}{2}} W_{0,\nu}(z), \quad (18)$$

from the result in Theorem 3, we obtain the following integral formula for the K -transform (see [4]) of the linear combination of the Bessel–Clifford functions:

$$\begin{aligned} & \int_0^\infty \left[\frac{1}{2} \cos(\theta\pi) p_2^{\theta-\frac{3}{2}} \hat{p}_2^{4.5-3\theta} \mathcal{C}_{3-2\theta}(p_2\hat{p}_2) - \frac{1}{2} \cos(\theta\pi) p_2^{3\theta-4.5} \hat{p}_2^{\frac{3}{2}-\theta} \mathcal{C}_{2\theta-3}(p_2\hat{p}_2) \right. \\ & \quad \left. - \frac{2(-1)^\theta}{\pi} \sin(\theta\pi) p_2^{3\theta-4.5} \hat{p}_2^{\frac{3}{2}-\theta} \mathcal{K}_{2\theta-3}(p_2\hat{p}_2) \right] K_{\theta-\frac{3}{2}}(\hat{p}_2) d\hat{p}_2 = K_{\theta-\frac{3}{2}}(p_2) \\ & \quad (p_2 \in \mathbb{R}^+, 1 < \text{Re}(\theta) < 2). \end{aligned} \quad (19)$$

Some similar results to those in Theorem 3 and formula (19) can be obtained from (17) in case $p_2 \in \mathbb{R}^-$.

Using the following three integral transformations:

(i) The first Hankel-Clifford integral transform (see, e.g., [7, Eq. (2.7)])

$$H_{\sigma}^{(1)}[f](\lambda) = \lambda^{\sigma} \int_0^{\infty} C_{\sigma}(\lambda \hat{\lambda}) f(\hat{\lambda}) d\hat{\lambda} \quad (\lambda \in \mathbb{R}^+);$$

(ii) The second Hankel-Clifford integral transform (see, e.g., [5]; see also [7, Eq. (2.9)])

$$H_{\sigma}^{(2)}[f](\lambda) = \int_0^{\infty} \hat{\lambda}^{\sigma} C_{\sigma}(\lambda \hat{\lambda}) f(\hat{\lambda}) d\hat{\lambda} \quad (\lambda \in \mathbb{R}^+);$$

(iii) The Macdonald-Clifford transform (see [12])

$$K_{\sigma}[f](\lambda) = \int_0^{\infty} \hat{\lambda}^{\sigma} K_{\sigma}(\lambda \hat{\lambda}) f(\hat{\lambda}) d\hat{\lambda} \quad (\lambda \in \mathbb{R}^+),$$

we can rewrite the identity in Theorem 3 in the following form:

$$\begin{aligned} & \frac{\cos(\theta\pi)}{2} \left[H_{3-2\theta}^{(1)} \left[\hat{p}_2^{4-3\theta} W_{\frac{q_1-p_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \right] (p_2) - H_{2\theta-3}^{(2)} \left[\hat{p}_2^{4-3\theta} W_{\frac{q_1-p_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \right] (p_2) \right] \\ & + \frac{2(-1)^{\theta} \Gamma(\frac{q_1-p_1}{2} - \theta)}{\pi \Gamma(\frac{p_1-q_1}{2} - \theta)} K_{2\theta-3} \left[\hat{p}_2^{4-3\theta} W_{\frac{p_1-q_1}{2}, \theta-\frac{3}{2}}(2\hat{p}_2) \right] (p_2) \\ & = (-1)^{\frac{p_1+q_1}{2}} p_2^{4-3\theta} W_{\frac{p_1-q_1}{2}, \theta-\frac{3}{2}}(2p_2). \end{aligned}$$

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